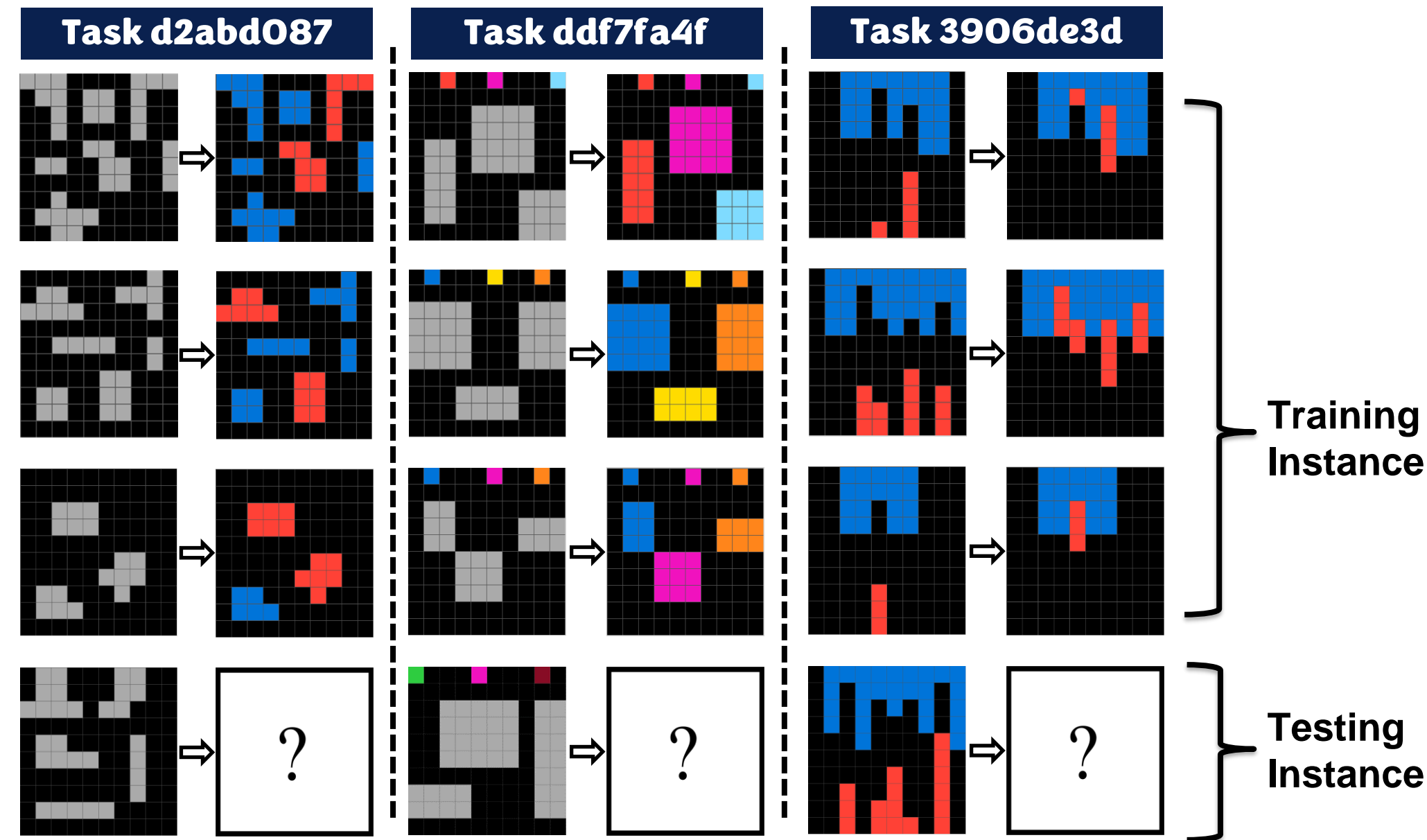


# Graphs, Constraints and Search for the Abstraction and Reasoning Corpus

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## Introduction

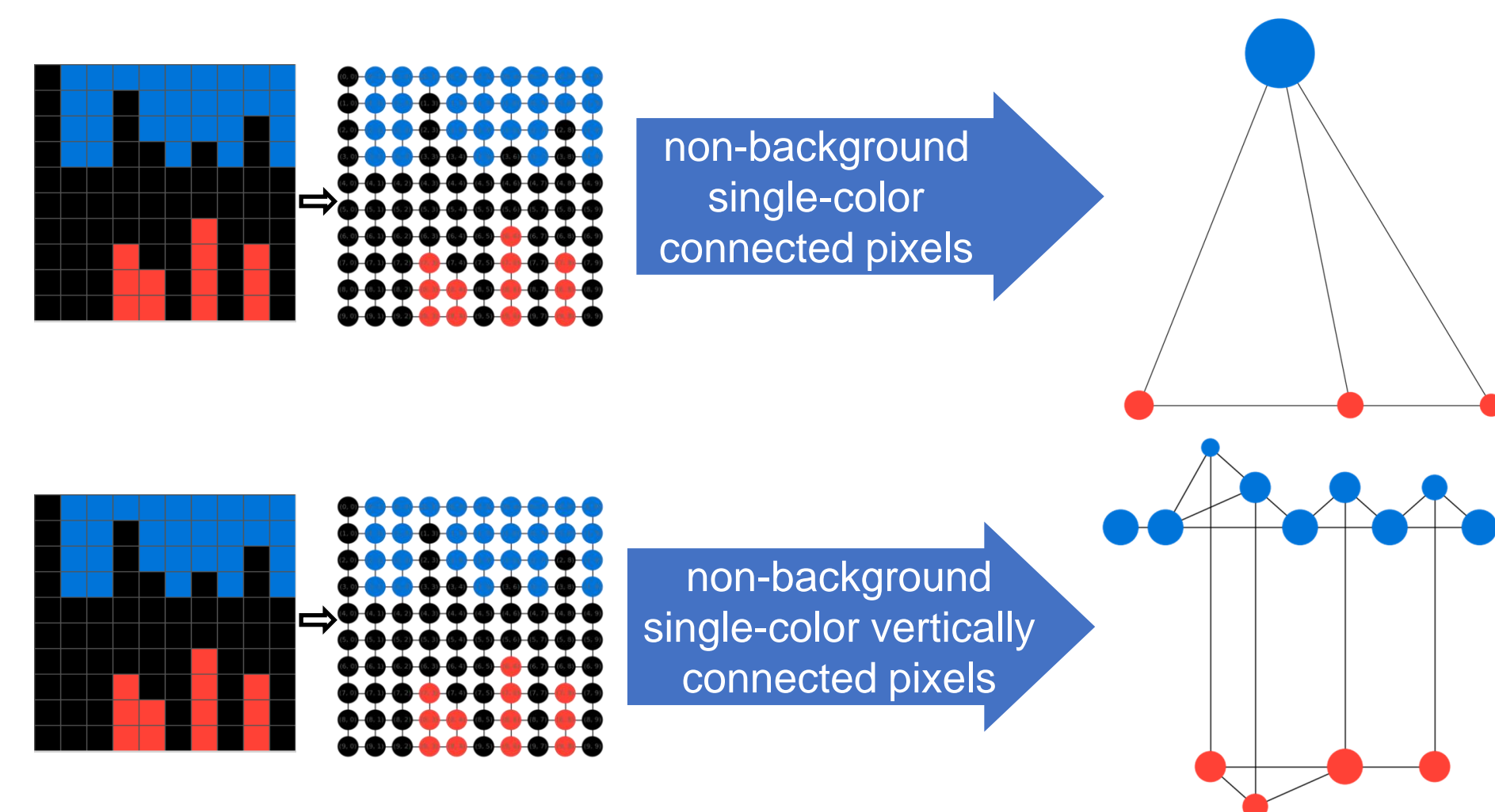


The Abstraction and Reasoning Corpus (ARC) [1] is a collection of 1000 image-based reasoning tasks. We propose Abstract Reasoning with Graph Abstractions (ARGA): an object-centric framework for solving the ARC

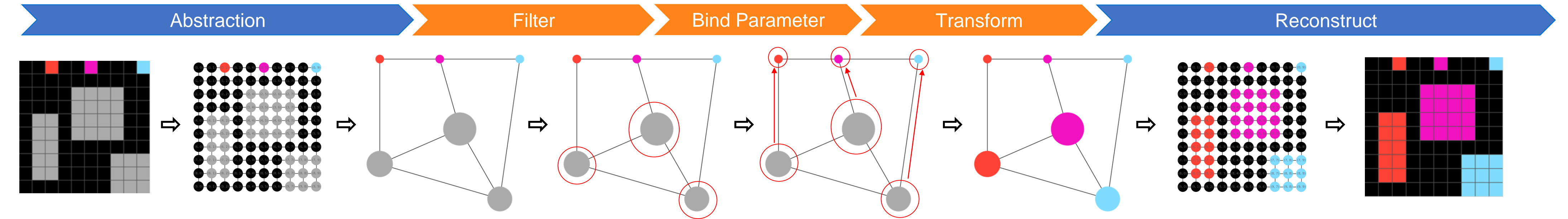
## Methods Overview

- Recognize objects through abstracted graph representations
- Define object-centric Domain Specific Language to represent the solution space
- Synthesize solution through constraint-guided search

## Recognize Objects: Graph Abstractions



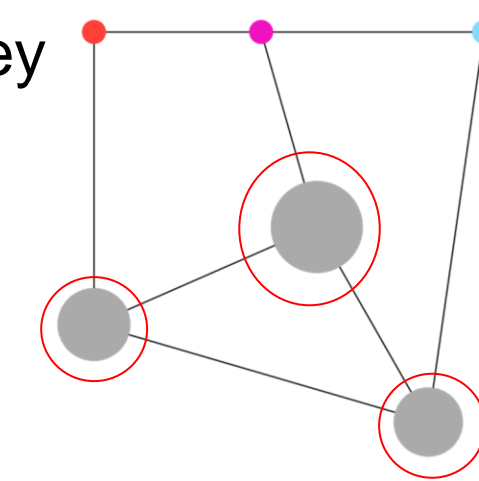
## Solution Space: Object-centric Domain Specific Language



**Filter** identify nodes that satisfy some condition

```
Filter(x)
::= Type(x)
::= Filter(x) ∧ Filter(x)
::= Filter(x) ∨ Filter(x)
::= ¬ Filter(x)
::= ∃y Rel(x, y) ∧ Filter(y)
::= ∃y Rel(y, x) ∧ Filter(y)
::= ∀y Rel(x, y) ⇒ Filter(y)
::= ∀y Rel(y, x) ⇒ Filter(y)
::= Rel(x, c) [c is a constant]
::= Rel(c, x) [c is a constant]
```

Filter for nodes with color grey  
 $filterByColorGrey(n) \equiv Node(n) \wedge color(n, grey)$

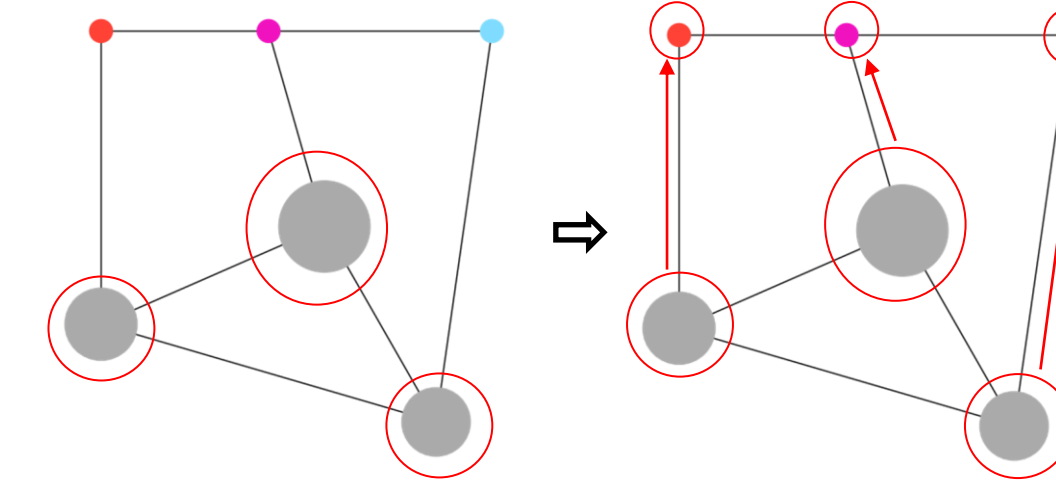


**Bind Parameter** retrieve values from the graph to use as transformation parameters

```
BindParam(x, v)
::= v = c [c is a constant]
::= Rel(x, v)
::= Rel(v, x)
::= ∃y Rel(x, y) ∧ Filter(y) ∧ Param(y, v)
::= ∃y Rel(y, x) ∧ Filter(y) ∧ Param(y, v)
```

Retrieve color of the size-1 neighbor

```
bindSize1NeighborColor(x, v) ≡
∃y neighbor(x, y) ∧ size(y, 1) ∧ color(y, v)
```

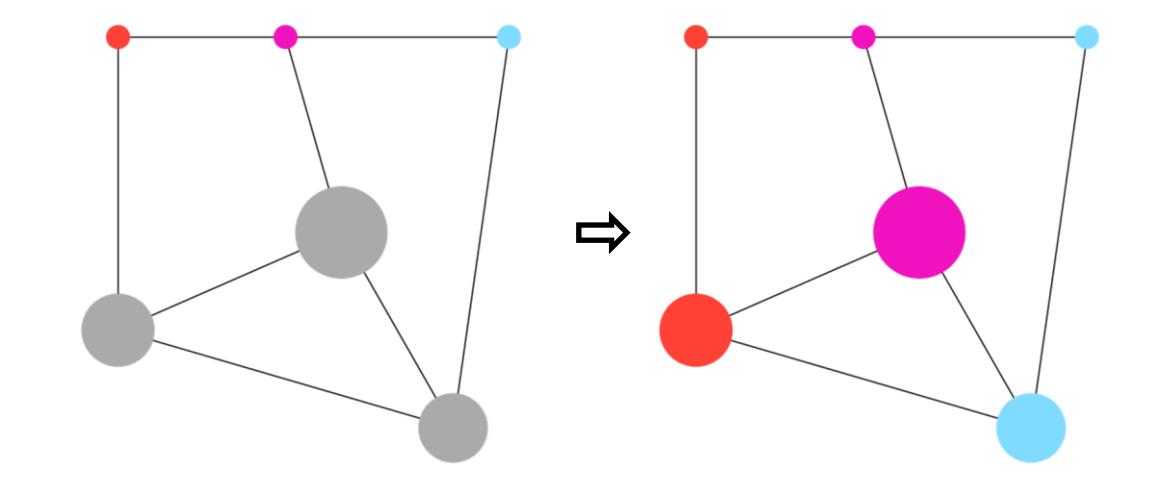


**Transform** updates object relations to reflect the desired changes

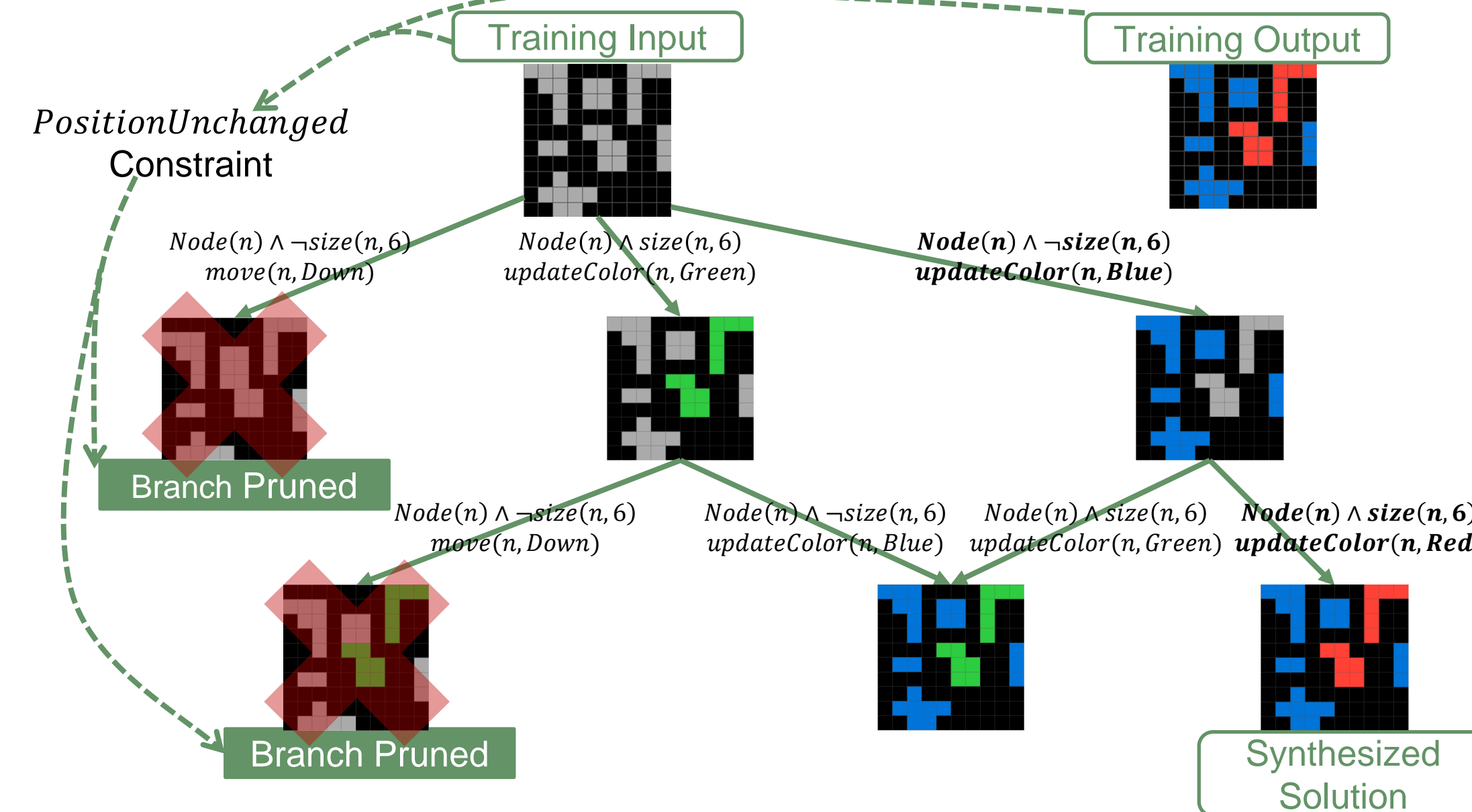
Transformation	Description
$updateColor(Node, Color)$	Update color of Node to Color
$Move(Node, Direction)$	Update pixels of Node to move in Direction
$Rotate(Node)$	Update pixels of Node to rotate it clockwise

Update the color of the selected nodes

```
updateColor(n : Node, c : Color)
→ color(n, c) ∧ ¬color(n, c') ∀c' ∈ Color s.t. c' ≠ c
```



## Synthesize Solution: Constraint-guided Search



## Results and Conclusion

Model	Task Type	# Training Correct	# Testing Correct	Average Nodes	Average Time (sec.)
ARGA	movement	18/31 (58.06%)	17/31 (54.84%)	3830.35	89.75
	recolor	25/62 (40.32%)	23/62 (37.10%)	12316.87	326.83
	augmentation	20/67 (29.85%)	17/67 (25.37%)	4668.82	67.09
	all	63/160 (39.38%)	57/160 (35.62%)	7504.81	178.66
State of the Art [2]	movement	21/31 (67.74%)	15/31 (48.39%)	2176777.67	62.45
	recolor	23/62 (37.10%)	28/62 (45.16%)	2290441.32	93.19
	augmentation	35/67 (52.24%)	21/67 (31.34%)	2248151.1	66.07
all	79/160 (49.38%)	64/160 (40.00%)	2249924.92	77.08	

Our ARGA framework uses **graph abstraction**, **domain-specific language**, and **constraint-guided search** to solve ARC tasks. Though its accuracy lags state-of-the-art methods, it significantly outperforms in terms of efficiency, exploring an order of magnitude fewer nodes.

[1] Chollet, F. 2019. On the Measure of Intelligence. arXiv:1911.01547.  
[2] top quarks. 2020. ARC-solution. <https://github.com/top-quarks/ARC-solution>.

